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# Naïve Bayes, KNN, KMeans & Decision Trees

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Tetherless World Constellation  
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# Contents

- Naïve Bayes
- Decision Trees
- k-Nearest Neighbors
- k-Means Clustering



# Naïve Bayes – what is it?

- Components of the Baye's Rule
- What does it mean by Naïve
- Naïve Bayes Classifier



# Naïve Bayes

- Naïve Bayes model uses a **probabilistic approach to do a classification.**
- In Naïve Bayes, the relationship between the input features and the classes are defined using the probabilities.
- Before diving into Naïve Bayes, you should understand the basic Probability Theories/Concepts.
- Probability is the measure of the likelihood that an event will occur.

[https://en.wikipedia.org/wiki/Naive\\_Bayes\\_classifier](https://en.wikipedia.org/wiki/Naive_Bayes_classifier)

<https://en.wikipedia.org/wiki/Probability>



# Naïve Bayes

- The class with the highest probability value determines the label for the sample.
- Naïve Bayes classifier uses the Bayes Theorem by Thomas Bayes.



[https://en.wikipedia.org/wiki/Naive\\_Bayes\\_classifier](https://en.wikipedia.org/wiki/Naive_Bayes_classifier)  
Image/Photo Credit: [https://en.wikipedia.org/wiki/Thomas\\_Bayes](https://en.wikipedia.org/wiki/Thomas_Bayes)



# Naïve Bayes

- In Naïve Bayes, **we assume that input features are statistically independent from each other**, which means, for a given class the value of one particular feature doesn't affect the value of another feature.
- **In reality, this assumption is little bit oversimplified and not true most of the time, because of that we say this assumption is *naïve***

[https://en.wikipedia.org/wiki/Naive\\_Bayes\\_classifier](https://en.wikipedia.org/wiki/Naive_Bayes_classifier)

[https://en.wikipedia.org/wiki/Bayes%27\\_theorem](https://en.wikipedia.org/wiki/Bayes%27_theorem)



# Probability ...

- Lets go over some definitions in probability.
- Probability is the measure of the likelihood that an event will occur.

- *Probability of event **A**:*

$$P(A) = \frac{\text{Number of ways for } A}{\text{Total number of possible outcomes}}$$

Reference: <https://en.wikipedia.org/wiki/Probability>

# Probability ...

- Before dive into Naïve Bayes, You should know/understand the two probability concepts:

- 1) Joint Probability
- 2) Conditional Probability

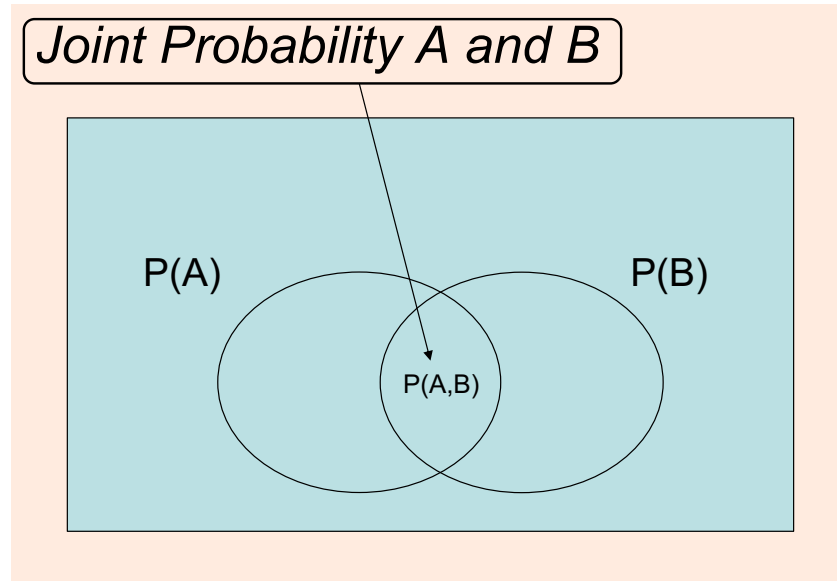
Reference: <https://en.wikipedia.org/wiki/Probability>





# Probability

**Joint Probability**: specifies the probability of event  $A$  and event  $B$  occurring together.



[https://en.wikipedia.org/wiki/Joint\\_probability\\_distribution](https://en.wikipedia.org/wiki/Joint_probability_distribution)



# Probability

**Joint Probability**: *specifies the probability of event A and event B occurring together.*

If the two events are independent,

What is the probability of getting two 6's when you roll two dice?

The probability of rolling(getting) two 6's:

$$P(A,B) = P(A) * P(B) = \frac{1}{6} * \frac{1}{6} = \frac{1}{36}$$



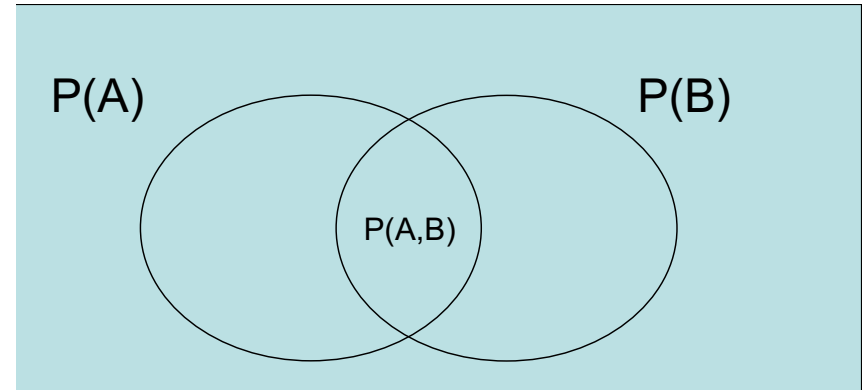
[https://en.wikipedia.org/wiki/Joint\\_probability\\_distribution](https://en.wikipedia.org/wiki/Joint_probability_distribution) Image/Photo Credit: [https://pngtree.com/freepng/two-dice\\_1504759.html](https://pngtree.com/freepng/two-dice_1504759.html)



# Probability

**Conditional Probability:** *probability of event A occurring, given that event B occurred.*

$$P(A|B) = \frac{P(A,B)}{P(B)} = \text{Probability of A, given B ; } P(B) > 0$$



[https://en.wikipedia.org/wiki/Conditional\\_probability](https://en.wikipedia.org/wiki/Conditional_probability)



# Bayes Theorem

- The relationship between conditional probabilities,  $P(B|A)$  and  $P(A|B)$  can be expressed using the Bayes Theorem.

$$P(B|A) = \frac{P(A|B) * P(B)}{P(A)}$$

Diagram illustrating the components of Bayes Theorem:

- Conditional Probability / Likelihood (points to  $P(A|B)$ )
- Prior Probability (points to  $P(B)$ )
- Posterior Probability (points to  $P(B|A)$ )
- Marginal Probability / evidence (points to  $P(A)$ )

~ Probability of cause given effect

Reference: [https://en.wikipedia.org/wiki/Bayes%27\\_theorem](https://en.wikipedia.org/wiki/Bayes%27_theorem)

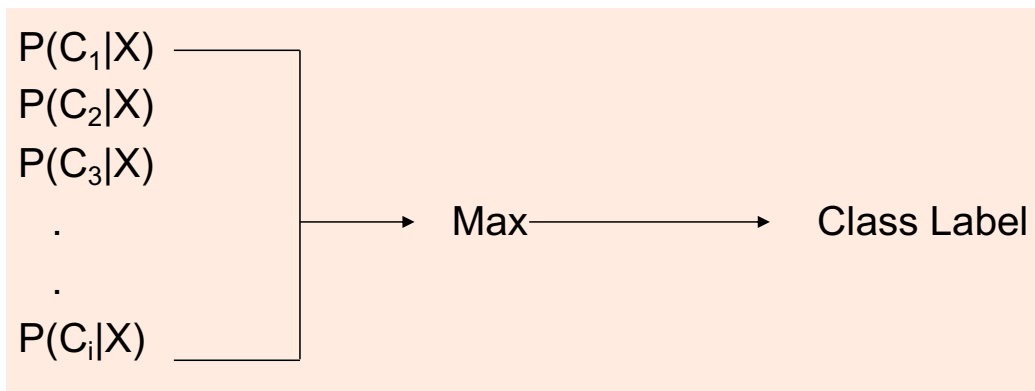


# Classification using Probabilities

- With given features  $X = (x_1, x_2, x_3, \dots, x_k)$

Predict the class  $C = (C_1, C_2, C_3, \dots, C_i)$

- We can do this by finding the value of  $C$  that, maximize the  $P(C|X)$



# Classification using Probabilities

- In order to find the class label  $C$ , we need to find the conditional probability of class  $C$  given  $X$  for all classes and choose the class that has the highest probability.
- It is difficult to estimate the  $P(C|X)$  so we use Bayes theorem to simplify this problem.

$$P(C|X) = \frac{P(X|C) * P(C)}{P(X)}$$

Diagram illustrating Bayes' Theorem for classification:

- $P(C|X)$  is labeled as **Posterior Probability**.
- $P(X|C)$  is labeled as **Conditional Probability / Likelihood**.
- $P(C)$  is labeled as **Prior Probability**.
- $P(X)$  is labeled as **Probability of observing X values for input features**.

# Bayes Theorem in Classification

These can be estimated from the training sample data

$$P(C|X) = \frac{P(X|C) * P(C)}{P(X)}$$

This is what we are looking for

It is a constant, and it can be ignored (probability of X doesn't depend on the class C, since it is same for all classes, it can be removed from the calculation of probability of C given X)

To find  $P(C|X)$  we only need to find the  $P(X|C)$  and  $P(C)$  which can be estimated from the data

# Bayes Theorem in Classification

- $P(x_k | C_i)$  is **estimated** from the training samples
  - Categorical: Estimate  $P(x_k | C_i)$  as percentage of samples of class  $i$  with value  $x_k$ 
    - Training involves counting percentage of occurrence of each possible value for each class
  - Numeric: Actual form of density function is generally not known, so “normal” density (i.e. distribution) is often assumed

$$\mathcal{N}(x|\mu, \sigma^2) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp \left\{ -\frac{1}{2\sigma^2} (x - \mu)^2 \right\}$$

[https://www.seas.upenn.edu/~cis520/papers/Bishop\\_2.3.pdf](https://www.seas.upenn.edu/~cis520/papers/Bishop_2.3.pdf)

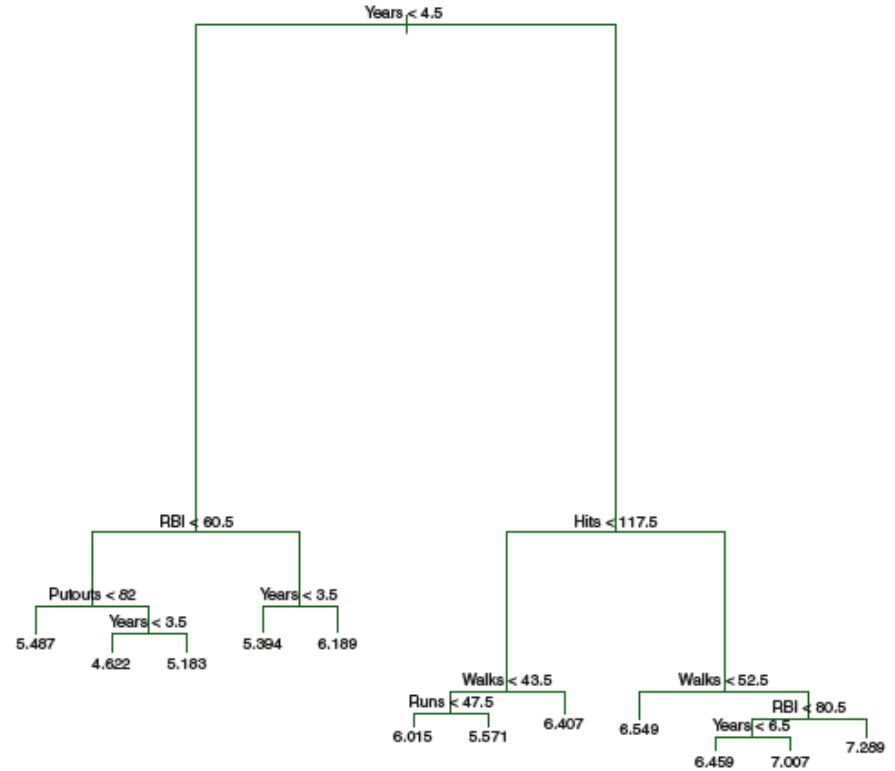


# Exercise: Naïve Bayes with iris

```
## Call the NaiveBayes Classifier Package e1071, which auto calls the Class package ##  
library("e1071")  
classifier<-naiveBayes(iris[,1:4], iris[,5])  
table(predict(classifier, iris[,-5]), iris[,5], dnn=list('predicted','actual'))  
classifier$apriori  
classifier$tables$Petal.Length  
  
                mean  Standard Deviation  
plot(function(x) dnorm(x, 1.462, 0.1736640), 0, 8, col="red", main="Petal length distribution for  
the 3 different species")  
  
curve(dnorm(x, 4.260, 0.4699110), add=TRUE, col="blue")  
curve(dnorm(x, 5.552, 0.5518947 ), add=TRUE, col = "green")
```

# Decision Trees

Decision trees can be applied to both regression and classification problems



**FIGURE 8.4.** Regression tree analysis for the **Hitters** data. The unpruned tree that results from top-down greedy splitting on the training data is shown.

Reference/Resources: Introduction to Statistical Learning with R -7 Edition: Chapter 8



# Advantages and Disadvantages of Decision Trees

Decision trees for regression and classification have number of advantages and disadvantages

## **Advantages:**

- Trees are very easy to explain to people, in fact, they are even easier to explain than linear regression.
- Some people believe that decision trees are more closely mirror human decision-making than other regression and classification techniques.
- Trees can be displayed graphically, and easily interpreted even non-experts (especially if the tree is small) can understand.

Reference/Resources: Introduction to Statistical Learning with R -7 Edition: Chapter 8

# Advantages and Disadvantages of Decision Trees

Decision trees for regression and classification have number of advantages and disadvantages

## Disadvantages:

- Unfortunately, trees generally do not have the same level of predictive accuracy as some of the other regression and classification approaches
- Additionally, trees can be very non-robust. In other words, a small changes in the data can cause a large change in the final estimated tree
- However, by aggregating many decision trees, using methods like *bagging*, *random forest* and *boosting*, the predictive performance of trees can be substantially improved.

# Decision Tree – Classification

- When we implement decision trees for classification, the idea is to split the data into subsets. So that each subset belongs to one particular class.
- In other words, splitting the data into regions, that are separated by decision boundaries, where each region's samples have only one class.

# Decision Tree

- Decision Tree has a hierarchical structure with “nodes” and “directed edges”
- The top node is defined as the “root node” and the nodes at the bottom are called as “leaf nodes”
- Nodes that are neither root node nor the leaf nodes are identified as “internal nodes” in the decision tree.
- There is a “class label” associated with each leaf node

# Decision Tree

- Classification decisions are made by traversing the decision tree
- Traversing starts from the root node (from the top of the tree).
- The root node and the internal nodes have test conditions. Those test conditions determine which path to traverse on the tree.

# Decision Tree

- **When a leaf node is reached through traversing, the category of the leaf node determines the classification.**
- **The depth is measured from the root node and the depth at the root node is zero.**
- **The depth of the decision tree:** Tree Depth is calculated by counting the number of edges in the longest path from the root node to a leaf node.



# Decision Tree

- Number of nodes in the decision tree determine the size of the tree.
- **The decision tree constructing algorithm is referred to as a tree induction algorithm.**

# Impurity Measure

- The goal is to have the resulting subsets to be homogeneous as possible and minimize the impurity.
- In practice, we don't get pure homogeneous subsets, there are impurities.
- **A common impurity measure to determining the best split is “Gini-index”**
- **The lower the Gini-index value, the higher the purity of the split.**

# Impurity Measure

- The decision tree will select the split that minimize the Gini-index.
- Besides the Gini-index, there are other impurity measures available such as:
  - entropy or information gain
  - misclassification rate

- The decision tree will test all variables to determine the best way to split a node using a purity measure such as Gini-index to compare different possibilities
- **Tree induction algorithms repeatedly split nodes to get more and more homogeneous subsets.**
- When this process stops? When does the algorithm stop growing the tree?

# When to Stop splitting the nodes?

- There are several criteria that can be used to determine the when a node shouldn't be split into subsets.
- **The induction algorithm can stop expanding a node when all samples in the node have the same class label.**
- Since getting pure subsets is difficult to archive with real world data, **the stopping criteria can be modified to archive certain percentage of the samples in the node. i.e 95% of have the same class label.**

# Stopping criteria

- Algorithm can stop expanding a node when the number of samples in the node falls below a certain minimum number.
- Induction algorithm can stop expanding a node when the improvement in impurity measure is way too small to measure (too small to make a much difference in classification result).
- Also, algorithm can stop expanding when it reach the maximum of the tree-depth.

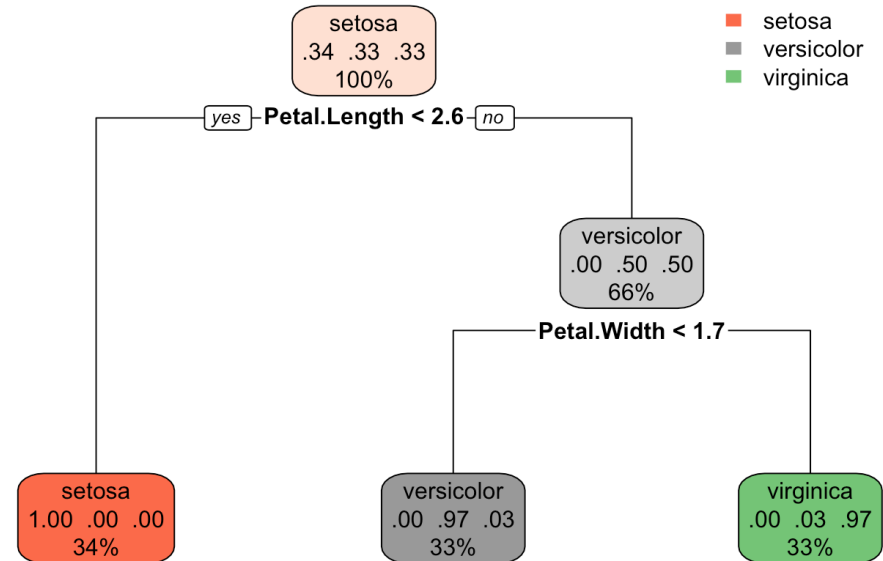
# Exercise: Random Forest

```
# Decision Trees --  
# Classification Tree  
# Install the following libraries/packages in RStudio library(rpart)  
library(rpart.plot)  
  
# we will be using the iris dataset  
iris  
dim(iris)  
# creating a sample from the iris dataset  
s_iris <- sample(150,100)  
s_iris  
  
# creat testing and training sets  
iris_train <-iris[s_iris,]  
iris_test <-iris[-s_iris,]  
dim(iris_test)  
dim(iris_train)
```

# Exercise: Random Forest

```
# generate the decision tree model  
dectionTreeModel <- rpart(Species~., iris_train,  
method = "class")  
dectionTreeModel
```

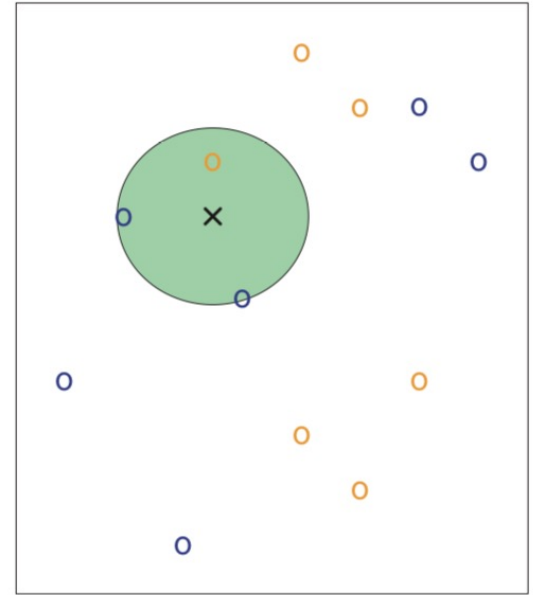
```
#plotting the decision tree model using  
#rpart.plot() function  
rpart.plot(dectionTreeModel)
```





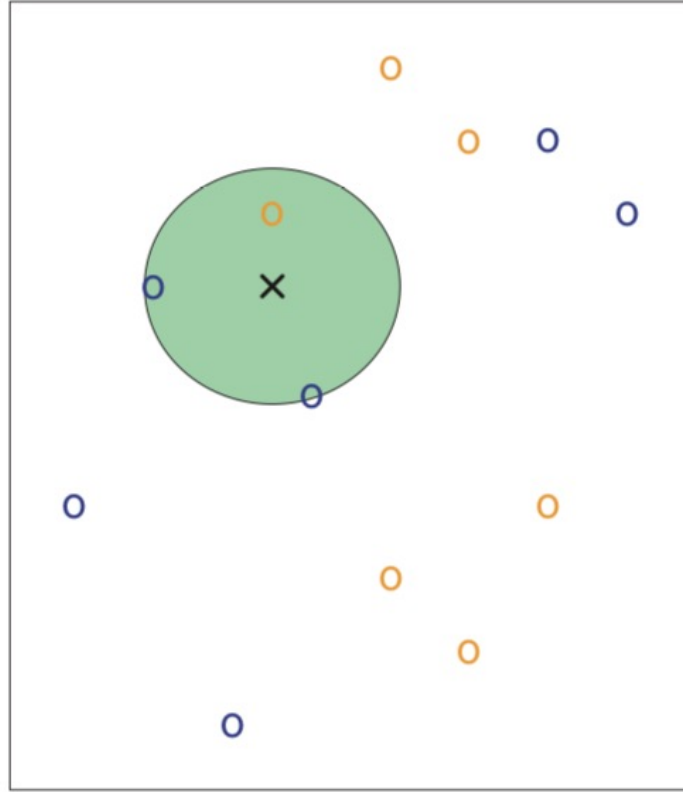
# kNN Classifier

- In the figure a dataset is shown consisting 6 blue and 6 orange observations.
- Our goal is to make a prediction for the point labeled by the black cross.
- Suppose we choose  $K=3$ , then KNN will first identify the three observations that are closest to the black cross as shown in the figure.
- This neighborhood is shown as a circle. It consist of 2 blue points and 1 orange point, resulting in estimated probabilities of  $2/3$  for the blue class and  $1/3$  for the orange class.
- Hence, kNN will predict that the black cross belongs to the blue class.



1. Image/photo Credit: Introduction to Statistical Learning with Applications in R, 7th Edition, Chapter 2  
Reference: Introduction to Statistical Learning with Applications in R, 7th Edition, Chapter 2 – KNN Classifier

# 6 blue points and 6 orange points



1. Image/photo Credit: Introduction to Statistical Learning with Applications in R, 7th Edition, Chapter 2  
Reference: Introduction to Statistical Learning with Applications in R, 7th Edition, Chapter 2 – KNN Classifier

# k-Means

- k-Means clustering is an unsupervised learning algorithm that, as the name hints, finds a fixed number ( $k$ ) of clusters in a set of data.
- A *cluster* is a group of data points that are grouped together due to similarities in their features. When using a K-Means algorithm, a cluster is defined by a *centroid*, which is a point (either imaginary or real) at the center of a cluster.
- Every point in a data set is part of the cluster whose centroid is most closely located. To put it simply, K-Means finds  $k$  number of centroids, and then assigns all data points to the closest cluster, with the aim of keeping the centroids small

Resource: <https://blog.easysol.net/machine-learning-algorithms-3/>  
<https://blog.easysol.net/author/acorrea/>

# K-Means Algorithm

```
randomly chose k examples as initial centroids
while true:
  create k clusters by assigning each
    example to closest centroid
  compute k new centroids by averaging
    examples in each cluster
  if centroids don't change:
    break
```

Resource: MIT 6.0002 lecture 12 ( MIT Open Courseware)  
<https://ocw.mit.edu/index.htm>

---

## Algorithm 10.1 *K-Means Clustering*

---

1. Randomly assign a number, from 1 to  $K$ , to each of the observations. These serve as initial cluster assignments for the observations.
2. Iterate until the cluster assignments stop changing:
  - (a) For each of the  $K$  clusters, compute the cluster *centroid*. The  $k$ th cluster centroid is the vector of the  $p$  feature means for the observations in the  $k$ th cluster.
  - (b) Assign each observation to the cluster whose centroid is closest (where *closest* is defined using Euclidean distance).

---

Reference: Introduction to Statistical Learning with Applications in R, 7<sup>th</sup> Edition, Chapter 10 – KMeans

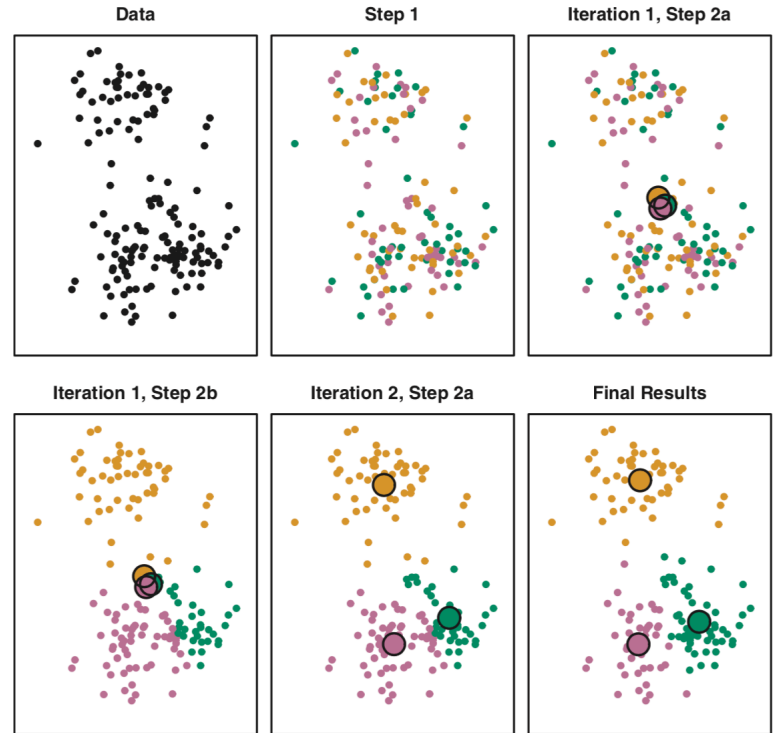
# K-Means Algorithm

---

## Algorithm 10.1 *K-Means Clustering*

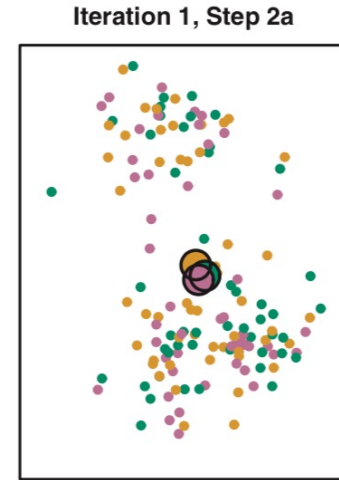
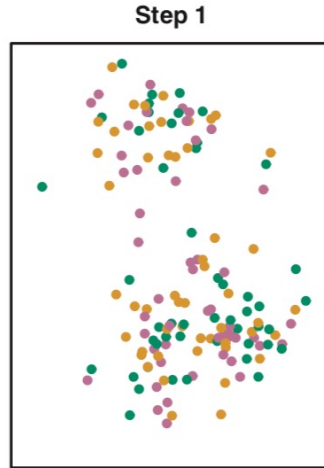
---

1. Randomly assign a number, from 1 to  $K$ , to each of the observations. These serve as initial cluster assignments for the observations.
  2. Iterate until the cluster assignments stop changing:
    - (a) For each of the  $K$  clusters, compute the cluster *centroid*. The  $k$ th cluster centroid is the vector of the  $p$  feature means for the observations in the  $k$ th cluster.
    - (b) Assign each observation to the cluster whose centroid is closest (where *closest* is defined using Euclidean distance).
- 



Reference: Introduction to Statistical Learning with Applications in R, 7<sup>th</sup> Edition, Chapter 10 – KMeans

# K-Means Algorithm



Observations (data) is shown

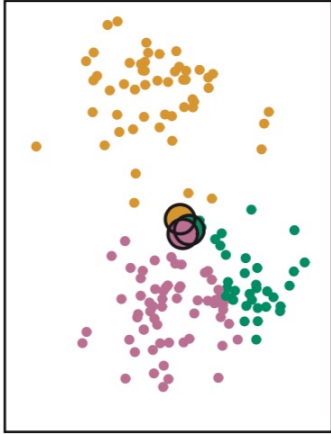
Step 1 of the algorithm: each observation is randomly assigned to a cluster

Iteration 1 Step 2(a): The cluster centroids are computed; these are shown in large colored disks. Initially centroids are almost completely overlapping because the initial cluster assignment were chosen at random

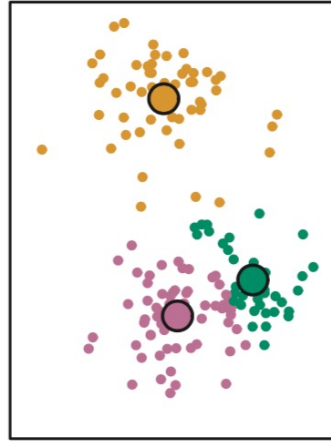
Reference: Introduction to Statistical Learning with Applications in R, 7<sup>th</sup> Edition, Chapter 10 – KMeans

# K-Means Algorithm

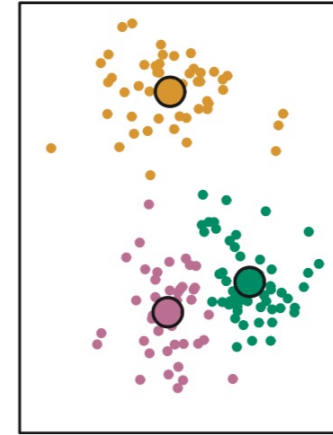
Iteration 1, Step 2b



Iteration 2, Step 2a



Final Results



Iteration 1 Step 2(b) : each observation is assigned to the nearest centroid

Iteration 2, Step 2(a): the step 2(a) is once again performed, leading to new cluster centroids.

Final Results: the results obtained after ten iterations. You can see the distinct clusters with their centroids.

**Image/Photo Credit:** Introduction to Statistical Learning with Applications in R, 7th Edition, Chapter 10 – KMeans  
Reference: Introduction to Statistical Learning with Applications in R, 7th Edition, Chapter 10 – KMeans

- K-Means clustering Animation
- <http://shabal.in/visuals/kmeans/6.html>



# In-Class Exercise: KNN - Abalone

```
# abalone dataset from UCI repository
# reading the dataset from UCI repository URL
abalone <- read.csv(url("https://archive.ics.uci.edu/ml/machine-learning-
databases/abalone/abalone.data"), header = FALSE, sep = ",")
# Column names
colnames(abalone) <- c("sex", "length", 'diameter', 'height', 'whole_weight', 'shucked_wieght',
'viscera_wieght', 'shell_weight', 'rings' )
# summary on abalone
summary(abalone)
# structure of the abalone data
str(abalone)
# summary of the abalone rings column
summary(abalone$rings)
```

# In-Class Exercise: KNN - Abalone

```
# As shown above, the "rings" variable has a range between 1-29.  
# This is the variable that we want to predict, and predicting this many levels  
# might not give us the insight we're looking for.  
# For now, we'll break the rings variable  
# into 3 levels" "young" for abalones less than 8, "adult" for abalones between 8-11,  
# and "old" for abalones older than 11.  
abalone$rings <- as.numeric(abalone$rings)  
abalone$rings <- cut(abalone$rings, br=c(-1,8,11,35), labels = c("young", 'adult', 'old'))  
abalone$rings <- as.factor(abalone$rings)  
summary(abalone$rings)  
# remove the "sex" variable in abalone, because KNN requires all numeric variables for prediction #  
z <- abalone  
aba <- abalone  
aba$sex <- NULL
```

# In-Class Exercise KNN – Abalone continue...

```
# normalize the data using min max normalization
normalize <- function(x) {return ((x - min(x)) / (max(x) - min(x))) }
aba[1:7] <- as.data.frame(lapply(aba[1:7], normalize))
summary(aba$shucked_wieght)
# After Normalization, each variable has a min of 0 and a max of 1.
# in other words, values are in the range from 0 to 1.
# We'll now split the data into training and testing sets.
ind <- sample(2, nrow(aba), replace=TRUE, prob=c(0.7, 0.3))
KNNtrain <- aba[ind==1,]
KNNtest <- aba[ind==2,]
sqrt(2918)
```

# In-Class Exercise KNN – Abalone continue...

```
# make k equal to the square root of 2918, the number of observations in the
training set.
# sqrt(2918) ~= 54.01852 round it to 55 and use k = 55
# We usually take an Odd number for k value,
# knn model
# knn() is in the "class" library. Make sure to install it first on your RStudio.
library(class)
help("knn") # Read the knn documentation on RStudio.
KNNpred <- knn(train = KNNtrain[1:7], test = KNNtest[1:7], cl =
KNNtrain$rings, k = 55)
KNNpred
table(KNNpred)
```

# In-Class Exercise K-Means Iris dataset

```
# iris dataset is from UCI ML repository.
```

```
library(ggplot2) # we will use ggplot2 to visualize the data.
```

```
head(iris) # first 6 rows of the
```

```
str(iris) # take a look at the structure of the iris data using str() function in R.
```

```
# dataset has 150 observations equally distributed observations among
```

```
# the three species: Setosa, Versicolor and Verginica.
```

```
summary(iris) # summary statistics of all the 4 variables Sepal.Length, Sepal.Width,
```

```
# Petal.Length and Petal.Width
```

```
help("sapply")
```

```
sapply(iris[,-5], var)
```

```
summary(iris)
```

# In-Class Exercise K-Means Iris dataset

```
# plot Sepal.Length Vs Sepal.Width using ggplot
ggplot(iris,aes(x = Sepal.Length, y = Sepal.Width, col= Species)) + geom_point()
# plot Petal.Length Vs Sepal.Width using ggplot
ggplot(iris,aes(x = Petal.Length, y = Petal.Width, col= Species)) + geom_point()
# kmeans clustering
# Read the documentation for kmeans() function
# https://stat.ethz.ch/R-manual/R-devel/library/stats/html/kmeans.html
set.seed(300)
k.max <- 12
# tot.withinss = Total within-cluster sum of square
# iter.max = the maximum number of iterations allowed
# nstart = if centers is a number, how many random sets should be chosen.
wss<- sapply(1:k.max,function(k){kmeans(iris[,3:4],k,nstart = 20,iter.max = 20)$tot.withinss})
```

# In-Class Exercise K-Means Iris dataset

wss # within sum of squares.

```
plot(1:k.max,wss, type= "b", xlab = "Number of clusters(k)", ylab = "Within cluster  
sum of squares") icluster <- kmeans(iris[,3:4],3,nstart = 20)
```

```
table(icluster$cluster,iris$Species)
```

# In the table we can see that most of the observations have been clustered correctly

# however, 2 of the versicolor have been put in the cluster with all the virginica

# and 4 of the verginica have been put in cluster 3 which mostly has versicolor.

# In-Class Exercises on Trees

```
# Classification ctrees
# iris data set
# Install the following libraries/packages library(rpart)
library(rpart.plot)
# we will be using the iris dataset
iris
dim(iris) # check the dimensions of the iris dataset
# creating a sample from the iris dataset s_iris <- sample(150,100)
s_iris
# creat testing and training sets iris_train <-iris[s_iris,]
iris_test <-iris[-s_iris,] dim(iris_test)
dim(iris_train)
# generate the decision tree model
dectionTreeModel <- rpart(Species~., iris_train, method = "class") dectionTreeModel
#plotting the decision tree model using rpart.plot() function rpart.plot(dectionTreeModel)
```



Thanks!